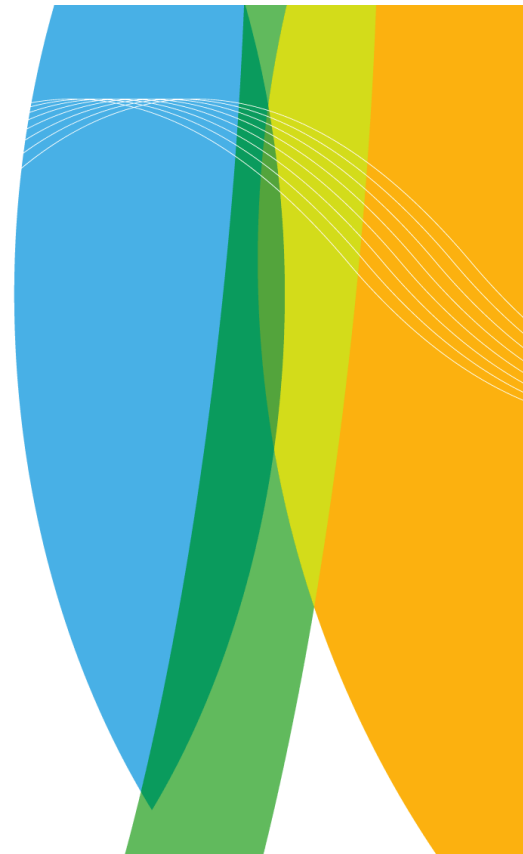


Alfven Waves and the Ionosphere

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Outline

- Background
- Properties of Alfven waves
 - Dispersion relation from ideal MHD
 - Different wave modes and their properties
- Alfven waves and the ionosphere
 - Ionospheric reflection coefficient
 - Field line oscillations
 - Ionospheric Alfven resonator



I: Background

There is a huge number of different wave modes in plasma, but **Alfven waves** are arguably the most important.

They carry energy, momentum, angular momentum and currents between different regions in the magnetosphere-ionosphere system.

Alfven speed v_A is the speed at which information is transmitted in plasma
 \Rightarrow Limit for time-step / grid spacing in MHD simulations.
 (Courant stability condition)

Ionospheric disturbances create Alfven waves,
 magnetospheric Alfven waves are reflected and modified at the ionosphere
 \Rightarrow ionosphere has an active role in M-I coupling

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II: Properties of Alfven waves

Derivation (see e.g. Koskinen, 2001)

Ideal MHD equations:

$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{V}) = 0$	Continuity of mass
$\rho \frac{\partial \mathbf{V}}{\partial t} + \rho (\mathbf{V} \cdot \nabla) \mathbf{V} = -\nabla p + \mathbf{J} \times \mathbf{B}$	Momentum equation
$\nabla p = v_s^2 \nabla \rho$	Equation of state (v_s is speed of sound)
$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}$	
$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$	Ohm's law in ideal MHD
$\mathbf{E} + \mathbf{V} \times \mathbf{B} = 0$	

Eliminate pressure, current and electric field.

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We end up with

$$\begin{aligned}\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{V}) &= 0 \\ \rho \frac{\partial \mathbf{V}}{\partial t} + \rho (\mathbf{V} \cdot \nabla) \mathbf{V} &= -v_s^2 \nabla \rho + \frac{1}{\mu_0} (\nabla \times \mathbf{B}) \times \mathbf{B} \\ \frac{\partial \mathbf{B}}{\partial t} &= \nabla \times (\mathbf{V} \times \mathbf{B}) \quad \text{Convection equation}\end{aligned}$$

Now assume static situation with *uniform magnetic field* \mathbf{B}_0 (in z-direction), *zero velocity* and *uniform density* ρ_0 . Then introduce *small perturbations*.

$$\begin{aligned}\mathbf{B}(\mathbf{r}, t) &= \mathbf{B}_0 + \mathbf{B}_1(\mathbf{r}, t) \\ \rho(\mathbf{r}, t) &= \rho_0 + \rho_1(\mathbf{r}, t) \\ \mathbf{V}(\mathbf{r}, t) &= \mathbf{V}_1(\mathbf{r}, t)\end{aligned}$$

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Linearize equations by taking only 1st order terms (0th order trivial, 2nd order very small):

$$\begin{aligned}\frac{\partial \rho_1}{\partial t} + \nabla \cdot (\rho_0 \mathbf{V}_1) &= 0 \\ \rho_0 \frac{\partial \mathbf{V}_1}{\partial t} &= -v_s^2 \nabla \rho_1 + \frac{1}{\mu_0} (\nabla \times \mathbf{B}_1) \times \mathbf{B}_0 \\ \frac{\partial \mathbf{B}_1}{\partial t} &= \nabla \times (\mathbf{V}_1 \times \mathbf{B}_0)\end{aligned}$$

These give equation for the velocity disturbance:

$$\frac{\partial^2 \mathbf{V}_1}{\partial t^2} - v_s^2 \nabla (\nabla \cdot \mathbf{V}_1) + v_A^2 \hat{\mathbf{e}}_z \times (\nabla \times [\nabla \times (\mathbf{V}_1 \times \hat{\mathbf{e}}_z)]) = 0$$

where $v_a = \frac{B_0}{\sqrt{\mu_0 \rho_0}}$ is Alfven speed and $\mathbf{B}_0 = B_0 \hat{\mathbf{e}}_z$

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Look for plane wave solutions, $\mathbf{V}_1(\mathbf{r}, t) = \mathbf{V}_1 e^{i(\mathbf{k} \cdot \mathbf{r} - \omega t)}$

After some algebra the previous equation reads:

$$-\omega^2 \mathbf{V}_1 + (v_s^2 + v_A^2)(\mathbf{k} \cdot \mathbf{V}_1) \mathbf{k} + v_A^2 (\mathbf{k} \cdot \hat{\mathbf{e}}_z) [(\mathbf{k} \cdot \hat{\mathbf{e}}_z) \mathbf{V}_1 - (\mathbf{V}_1 \cdot \hat{\mathbf{e}}_z) \mathbf{k} - (\mathbf{k} \cdot \mathbf{V}_1) \hat{\mathbf{e}}_z] = 0$$

This is *dispersion equation* for Alfvén waves.

The uniform background magnetic field, \mathbf{B}_0 , is in z-direction.

Choose

$$\mathbf{k} = k(\hat{\mathbf{e}}_x \sin \theta + \hat{\mathbf{e}}_z \cos \theta)$$

$$\mathbf{V}_1 = V_{1x} \hat{\mathbf{e}}_x + V_{1y} \hat{\mathbf{e}}_y + V_{1z} \hat{\mathbf{e}}_z$$

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The dispersion equation in component form is

$$\begin{bmatrix} -\omega^2 + k^2 v_A^2 + k^2 v_s^2 \sin^2 \theta & 0 & k^2 v_s^2 \sin \theta \cos \theta \\ 0 & -\omega^2 + k^2 v_A^2 \cos^2 \theta & 0 \\ k^2 v_s^2 \sin \theta \cos \theta & 0 & -\omega^2 + k^2 v_s^2 \cos^2 \theta \end{bmatrix} \cdot \begin{pmatrix} V_{1x} \\ V_{1y} \\ V_{1z} \end{pmatrix} = 0$$

There are non-zero solutions for \mathbf{V}_1 only if the determinant is zero.

Three different cases:

$$\omega^2 = k^2 v_A^2 \cos^2 \theta$$

Alfvén mode

$$\omega^2 = \frac{k^2}{2} \left(v_A^2 + v_s^2 \pm \sqrt{(v_A^2 + v_s^2)^2 - 4 v_A^2 v_s^2 \cos^2 \theta} \right)$$

Fast (+) and slow (-) modes

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Alfven mode (aka shear or transversal or intermediate Alfven wave)

Alfven mode dispersion relation $-\omega^2 + v_A^2 k_{\parallel}^2 = 0$ (with $k_{\parallel} = k \cos \theta$) tells us that the velocity disturbance \mathbf{V}_1 (and also \mathbf{E}_1 and \mathbf{B}_1) satisfies

$$\partial_t^2 \mathbf{V}_1 - v_A^2 \nabla_{\parallel}^2 \mathbf{V}_1 = 0$$

In general this has a solution

$$\mathbf{V}_1 = \mathbf{V}_1^{\uparrow\uparrow}(\mathbf{r}_{\perp}, r_{\parallel} - v_A t) + \mathbf{V}_1^{\uparrow\downarrow}(\mathbf{r}_{\perp}, r_{\parallel} + v_A t)$$

We see that the Alfven mode waves propagate only parallel or anti-parallel to the background magnetic field and not at all perpendicular to it.

From dispersion relation we also get

phase speed $\omega/k = v_A |\cos \theta|$ and group velocity $\nabla_k \omega = \pm v_A \hat{\mathbf{e}}_{\parallel}$
(upper sign for parallel propagation)

NOTE: \parallel and \perp are with respect to the background field \mathbf{B}_0

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Properties of the wave fields:

- Velocity disturbance is perpendicular to background field and wave vector, $\mathbf{V}_1 \cdot \mathbf{k} = 0 = \mathbf{V}_1 \cdot \mathbf{B}_0$
- Magnetic disturbance from convection equation, $\mathbf{B}_1 = \mp (B_0 \mathbf{V}_1) / v_A$
- No density or pressure disturbance.
- Electric disturbance from Ohm's law, $\mathbf{E}_1 = -\mathbf{V}_1 \times \mathbf{B}_0$
- The wave carries a field aligned current (FAC) $j_{\parallel} = \mp i B_0 k_{\perp} V_1 / (\mu_0 v_A)$
- Poynting flux is $\mathbf{S} = \mathbf{E}_1 \times \mathbf{B}_1 / \mu_0 = \pm (B_0^2 V_1^2) / (\mu_0 v_A) \hat{\mathbf{e}}_{\parallel}$

Also note:

- Relation between electric and magnetic disturbances $\mathbf{B}_1 = \mp (\mathbf{E}_1 \times \hat{\mathbf{e}}_{\parallel}) / v_A$
- Perpendicular electric field is a potential field, $(\nabla \times \mathbf{E}_{1\perp})_{\parallel} = 0$
- Relation between FAC and perpendicular electric field $j_{\parallel} = \pm \Sigma_A \nabla_{\perp} \cdot \mathbf{E}_{1\perp}$
where $\Sigma_A = 1 / (\mu_0 v_A)$ is Alfven conductance.

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Alfven wave with \mathbf{k} parallel to \mathbf{B}_0 .

Magnetic field is not compressed,
only undulating ==> no density
disturbance (frozen-in condition).

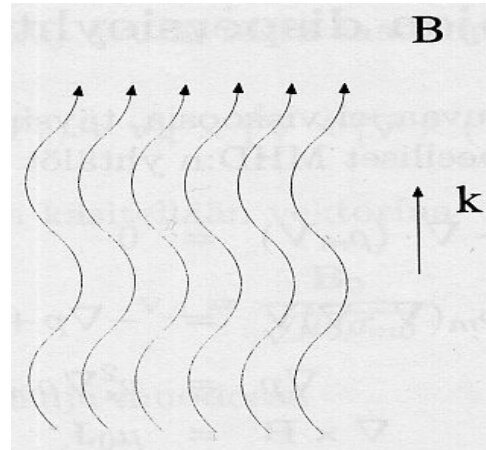


Figure from Koskinen (2001)

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Fast mode (aka compressional or fast magnetosonic / Alfvén wave)

In warm plasma $v_s > 0$ and dispersion relation is complicated.
Group velocity is not parallel to \mathbf{k} and depends on direction and frequency.

In cold plasma magnetic pressure \gg kinetic pressure. Then also
 $v_A \gg v_s$ and the dispersion relation simplifies to $\omega^2 = k^2 v_A^2$
Now group and phase velocities are equal and isotropic, $\nabla_{\mathbf{k}} \omega = v_A \hat{\mathbf{e}}_k$
so the fast mode propagates in all directions.

Properties of the wave fields: (in cold plasma)

- Velocity disturbance is in the direction of the perpendicular wave vector,
 $\mathbf{V}_1 \cdot \mathbf{B}_0 = 0, \quad \mathbf{V}_1 \cdot \mathbf{k} = V_1 k_{\perp}$
- Magnetic disturbance is $\mathbf{B}_1 = (-B_0 \cos \theta \mathbf{V}_1 + V_1 \sin \theta \mathbf{B}_0) / v_A$

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- Electric disturbance is $\mathbf{E}_1 = -\mathbf{V}_1 \times \mathbf{B}_0$
- There is also a density disturbance $\rho_1 = -(\rho_0 V_1 \sin \theta) / v_A$
- Field aligned current is zero, $\mathbf{j} \cdot \mathbf{B}_0 = 0$
- The Poynting flux is $\mathbf{S} = (B_0^2 V_1^2) / (\mu_0 v_A) \hat{\mathbf{e}}_k$
- The perpendicular electric field $\mathbf{E}_{1\perp}$ is divergence-free,
 $\nabla_{\perp} \cdot \mathbf{E}_{1\perp} = 0, \quad (\nabla \times \mathbf{E}_{1\perp})_{\parallel} = (V_1 B_0 \sin \theta) / v_A$

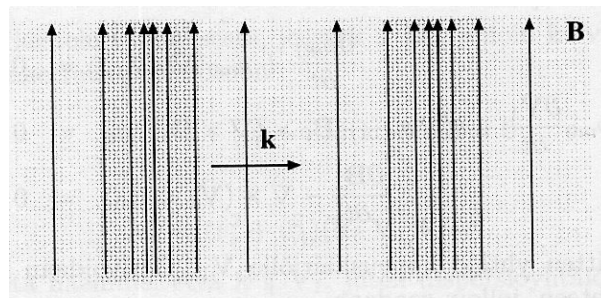


Figure from
Koskinen (2001)

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Slow mode (aka slow magnetosonic or Alfvén wave)

This mode disappears in cold plasma.

In the magnetosphere we might have $v_A \sim 1000$ km/s and $v_s \sim 10$ km/s.
 \Rightarrow plasma is quite cold.

Home exercise: Derive the properties of slow and fast mode waves in warm plasma.

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Some complications

- In some situations v_A could exceed c
==> Need to include $c^{-2} \partial_t \mathbf{E}$ term.
- In the magnetosphere typical $v_A \sim 1000$ km/s, observed geomagnetic pulsation have periods 10 - 600 s ==> wavelength 2-100 Earth radii.
==> Background \mathbf{B}_0 , ρ_0 , \mathbf{V}_0 non-uniform and perhaps time-dependent.
- In the ionosphere the Ohm's law is $\mathbf{J} = \bar{\bar{\sigma}} \cdot \mathbf{E}$

with
$$\bar{\bar{\sigma}} = \begin{bmatrix} \sigma_P & -\sigma_H & 0 \\ \sigma_H & \sigma_P & 0 \\ 0 & 0 & \sigma_{\parallel} \end{bmatrix}$$

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III: Alfven waves and the ionosphere

Reflection at the ionosphere

- Simplified model:
- \mathbf{B}_0 is uniform and in z-direction (z positive downward)
 - Ionosphere is a thin sheet at $z=0$ with uniform Hall and Pedersen conductances
 - Ideal magnetospheric plasma above, $z < 0$
 - Neutral atmosphere below, $z > 0$

Above ionosphere we have the ideal MHD wave modes. Assume that there is no incident fast mode wave, for fast waves are not guided by the magnetic field ==> geometric attenuation.

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Electric field of the incident and reflected waves is $\mathbf{E}_\perp = \mathbf{E}_\perp^\downarrow + \mathbf{E}_\perp^\uparrow$

They carry field aligned current $j_\parallel = \Sigma_A \nabla \cdot (\mathbf{E}_\perp^\downarrow - \mathbf{E}_\perp^\uparrow)$

In the ionosphere we have Ohm's law $\mathbf{J}_\perp = \Sigma_P \mathbf{E}_\perp - \Sigma_H \mathbf{E}_\perp \times \hat{\mathbf{e}}_\parallel$

and the field aligned current is

$$j_\parallel = \nabla \cdot \mathbf{J}_\perp = \Sigma_P \nabla \cdot \mathbf{E}_\perp + \mathbf{E}_\perp \cdot (\nabla \Sigma_P) - \Sigma_H \hat{\mathbf{e}}_\parallel \cdot (\nabla \times \mathbf{E}_\perp) - (\mathbf{E}_\perp \times \hat{\mathbf{e}}_\parallel) \cdot (\nabla \Sigma_P)$$

If we assume *uniform conductances* and *non-rotational electric field*, we have relation

$$\Sigma_P \nabla \cdot (\mathbf{E}_\perp^\downarrow + \mathbf{E}_\perp^\uparrow) = \Sigma_A \nabla \cdot (\mathbf{E}_\perp^\downarrow - \mathbf{E}_\perp^\uparrow)$$

$$\Rightarrow \mathbf{E}_\perp^\uparrow = R_I \mathbf{E}_\perp^\downarrow \quad \text{with } R_I = \frac{\Sigma_A - \Sigma_P}{\Sigma_A + \Sigma_P}$$

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Magnetic field above the ionosphere is

$$\mathbf{B}^{above} = \frac{1}{v_A} (-\mathbf{E}_\perp^\downarrow + \mathbf{E}_\perp^\uparrow) \times \hat{\mathbf{e}}_\parallel = \frac{-2 \Sigma_P}{v_A (\Sigma_A + \Sigma_P)} \mathbf{E}_\perp^\downarrow \times \hat{\mathbf{e}}_\parallel$$

At the ionosphere there is a jump in the magnetic field given by

$$\Delta \mathbf{B}_\perp = \mu_0 \mathbf{J}_\perp \times \hat{\mathbf{e}}_\parallel = \frac{2}{v_A (\Sigma_A + \Sigma_P)} (\Sigma_P \mathbf{E}_\perp^\downarrow \times \hat{\mathbf{e}}_\parallel - \Sigma_H \mathbf{E}_\perp^\downarrow)$$

Below the ionosphere the magnetic field is

$$\mathbf{B}^{below} = \mathbf{B}^{above} + \Delta \mathbf{B}_\perp = \frac{-2 \Sigma_H}{v_A (\Sigma_A + \Sigma_P)} \mathbf{E}_\perp^\downarrow$$

Magnetic field is rotated by 90 degrees and amplified by Σ_H / Σ_P at the ionospheric boundary.

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More realistic model:

- Inhomogeneous conductances: Introduce a wave potential for the reflected wave, $E_{\perp}^{\uparrow} = -\nabla \phi$. FAC condition gives a diff. eq. for ϕ (Glassmeier, 1984).
- Inductive processes: Mode conversion occurs in the reflection, incident shear wave --> reflected shear and fast waves (Yoshikawa and Itonaga, 1996; Buchert, 1997).
- Oblique background magnetic field (Sciffer et al., 2004).
- All of the above + 3D ionosphere + non-linear effects: Numerical, more or less MHD-type approaches (e.g. Streltsov and Lotko, 2004; Lysak, 2004; Dreher, 1997).

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Field line oscillations

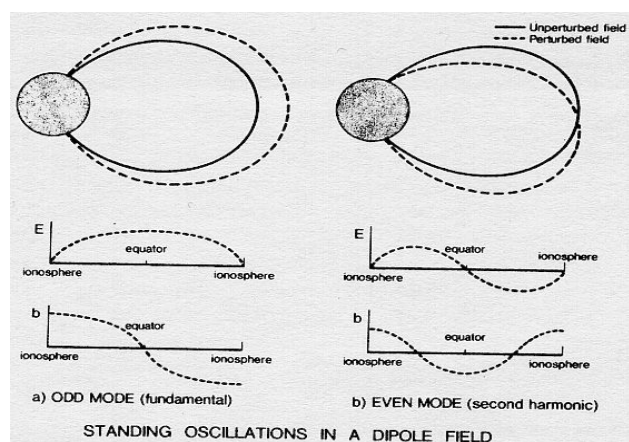
Figure from Hughes (1983)

Standing shear Alfvén waves reflecting between northern and southern ionospheres.

==>

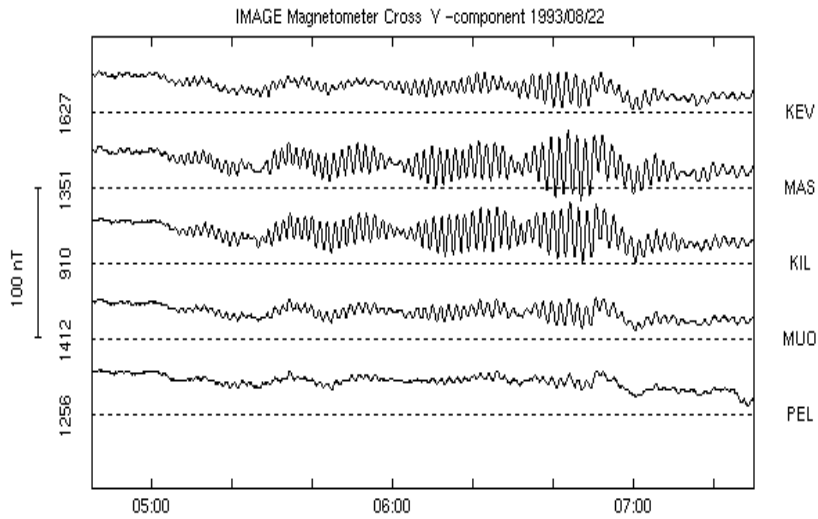
Discrete frequency spectra in mHz range.

Analytical solution for Alfvén waves in dipole geometry exists.



See e.g. Hughes (1983) or Oulu textbook for further information.

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Giant pulsations observed with the IMAGE magnetometer network.

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Ionospheric waveguide

- Under some conditions fast magnetosonic waves can be trapped in the ionospheric F-layer. These waves can propagate across magnetic field
==> ionospheric waveguide
- These guided waves are associated with so called pc1 pulsations in the ground magnetic field.
- Fast waves are created locally, when a magnetospheric disturbance is transmitted to ionosphere.
==> Waveguide transmits disturbances over large areas in the ionosphere

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Results from a simulation where an incident shear wave excites fast mode waves in the waveguide.

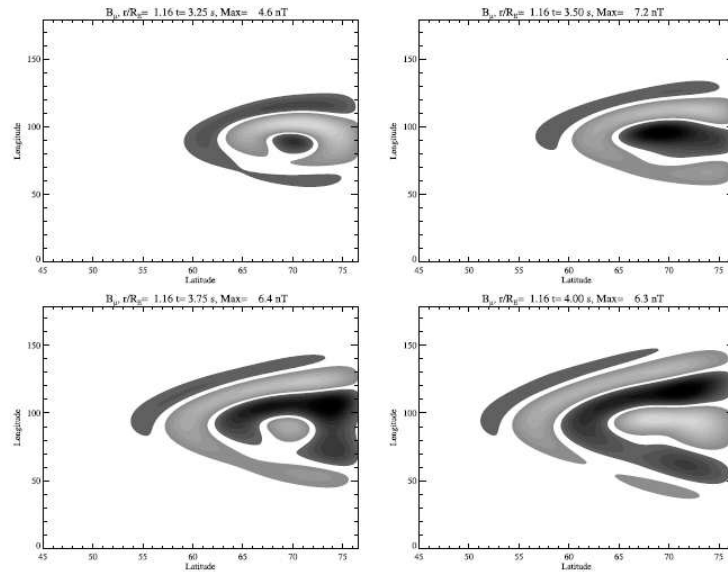


Figure from Lysak (2004)

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Ionospheric Alfvén resonator (IAR)

- Alfvén waves are reflected from ionosphere because of the sudden change in conductivity.
 - Also large gradients in Alfvén velocity cause reflection.
 - Alfvén velocity has a maximum ~ 1 Earth radii above the ionosphere.
- ==> Resonant cavity may form between ionosphere and velocity maximum.

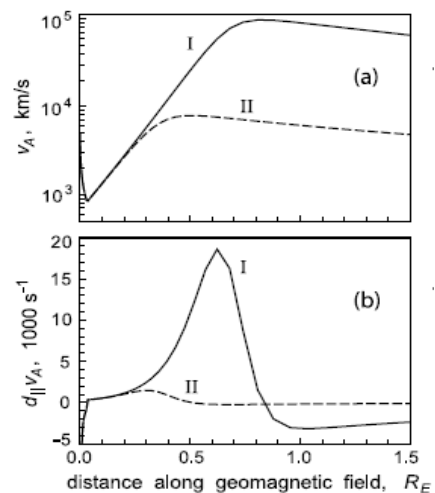


Figure from Streltsov and Lotko (2004)

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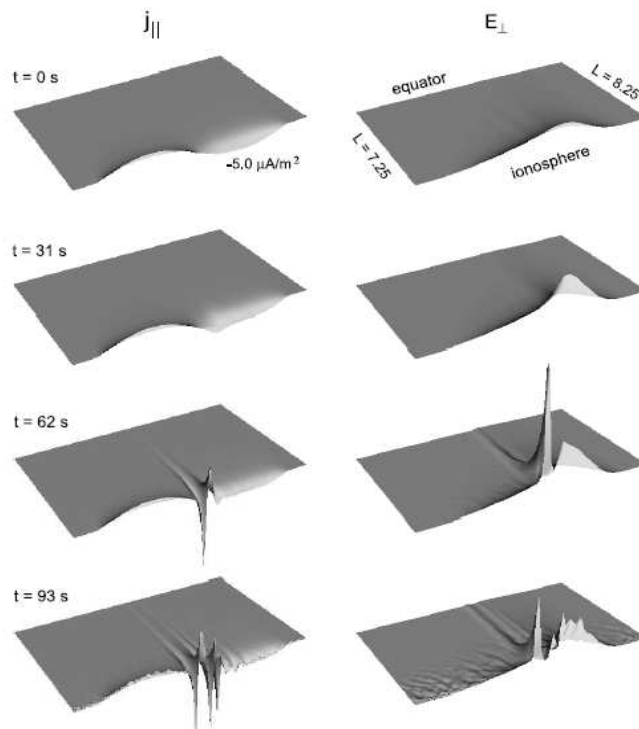


Ionospheric Alfvén
resonator may amplify
weak disturbances

==>

Ionosphere generates
small scale structures
by itself.

Figure from Streltsov
and Lotko (2004)



Sources

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